



VOTOL EM Controller Program Manual

It is forbidden to non-specialists use!



This manual was explained in detail for the IV generation EM series controller, which update download illustrates and parameter adjustment.

Before using the software, please read this manual. In order to facilitate the operation, please keep this manual.

In order to make the software of maximum utility, please make sure the end user to use this manual.

Please be sure to read the manual carefully before starting the operation.

Disclaimer:

For the IV generation of EM series controller program updates and parameter adjustment can only be done by professional and technical personnel.

If without the written permission of our company for the IV VOTOL generation EM series, the application update to download and parameter of the controller adjustment is not allowed.

It is forbidden to non-professional personnel operate this software.

In the above event, our company will no longer be responsible for accident happens by controller.

1. Software installation (only support win 7/10)



1.1 USB Driver Installation

(1) Download the "USB-to-serial-win 10-20150814" file, decompressing file.

 USB-to-serial-win10-20150814	2016/12/26 10:44	WinRAR 压缩文件	6,422 KB
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(2) choose the suitable driver with your computer for installation.





win7,win8, win 10 are available.

 win_me_2000_XP USB-to-Serial	2013/3/8 14:38	WinRAR ZIP 压缩...	1,586 KB
 windows 7 10 32 64 USB-to-Serial ...	2013/3/8 14:38	WinRAR ZIP 压缩...	2,390 KB

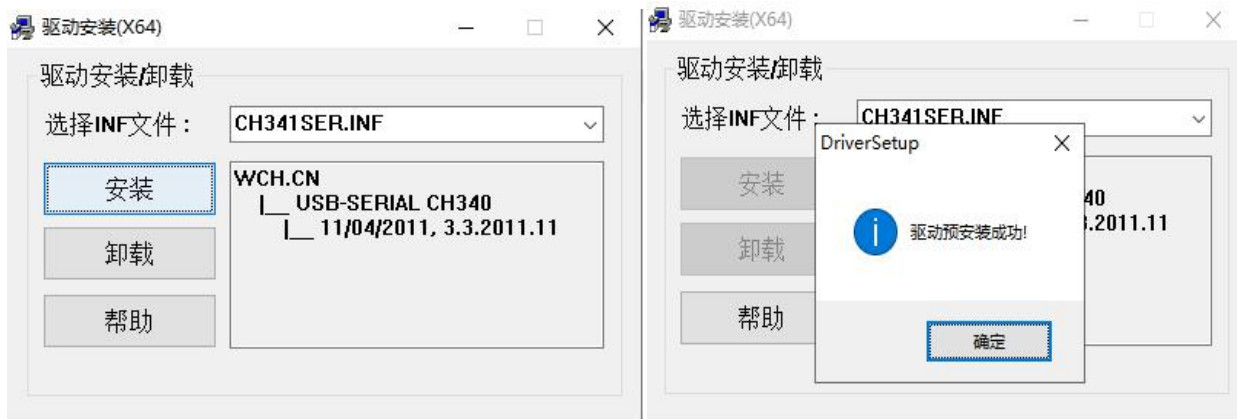
1.11. Decompress the operation first

 Setup 32.64位元	2012/8/3 12:31	应用程序	3,075 KB
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2. Unzip the YH-340 USB package and select CH341SER.EXE to install it.

 windows 7 8 10 32 64	2019-08-07 13:52	文件夹	
 YH-340 USB	2019-08-23 10:29	文件夹	
 win_me_2000_XP USB-to-Serial	2013-03-08 14:38	360压缩 ZIP 文件	1,586 KB
 简介	2015-08-07 10:56	文本文档	2 KB

 CH341SER.EXE	227.6 KB	178.8 KB	应用程序	2012-08-03 12:30
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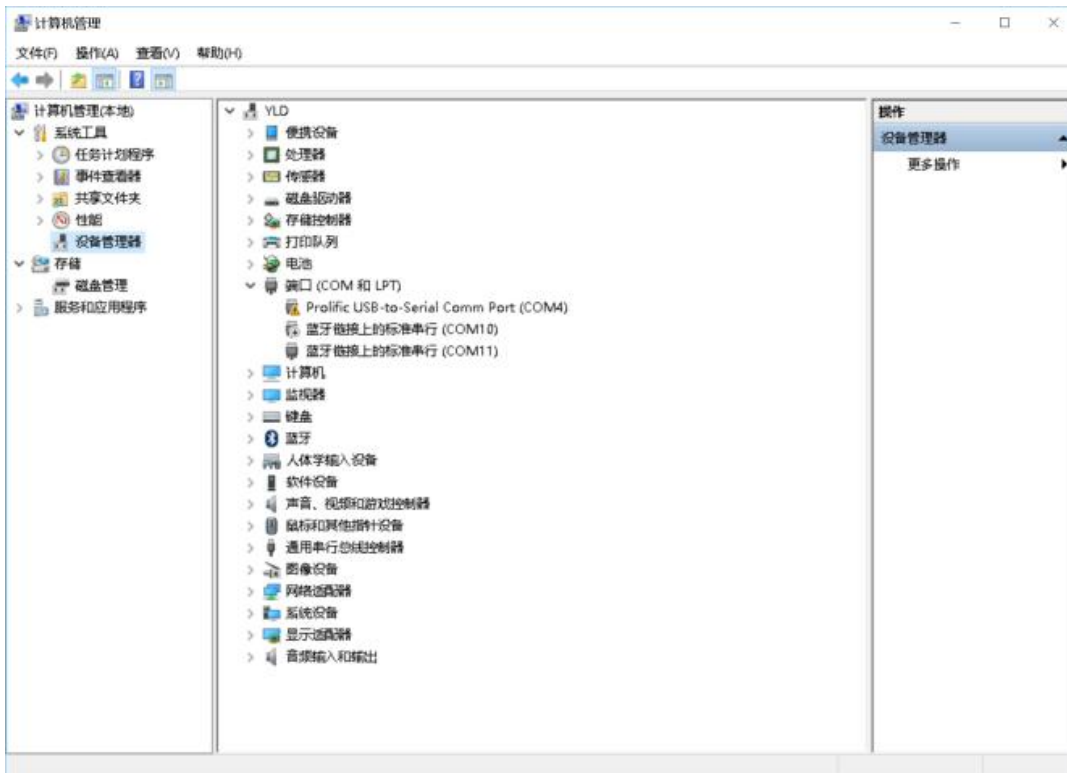


Follow the steps above to install

(3) After installation, pls. connect the USB cable with controller and computer. If it's unable to connect, pls. Check below steps.



Right click "my computer" in the desktop



then click “device manager”

choose “port(COM & LPT)”

choose the COM with “!”, click “search automatically for updated driver software”



Close the software when you finish

After running, please run the software directly: EM_V3 series debugging program;

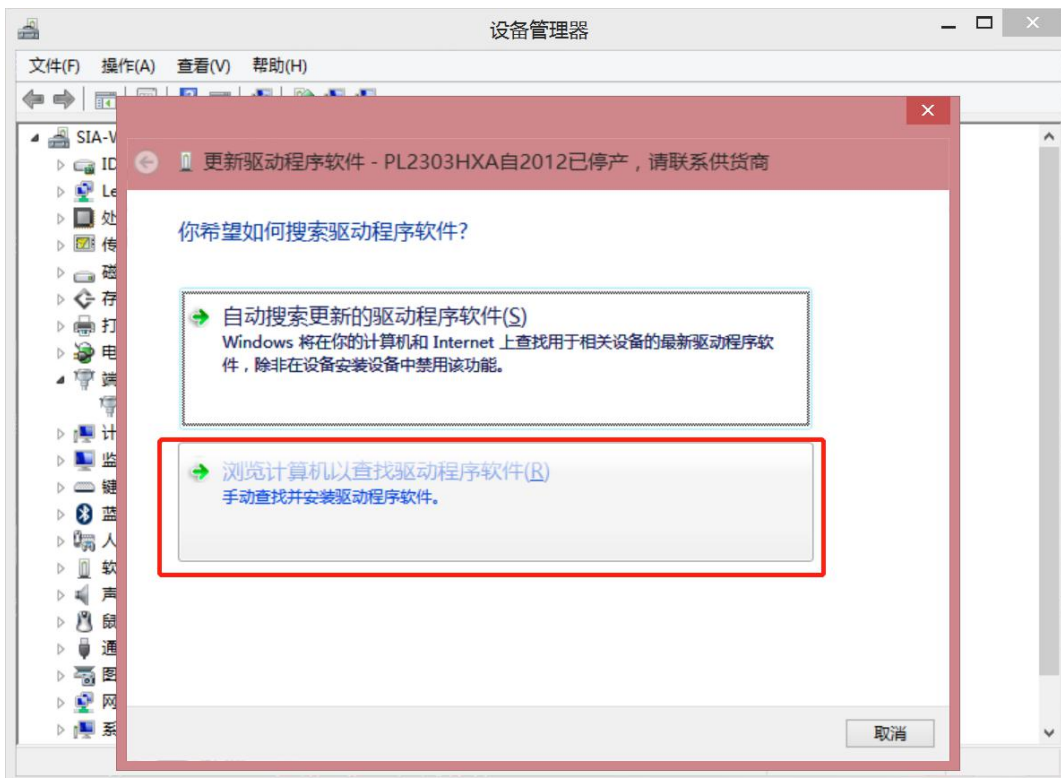
If the port has”自 2012 已停产，请联系供货商 处理方法(Pls contact supplier if it is stop production since 2012)”



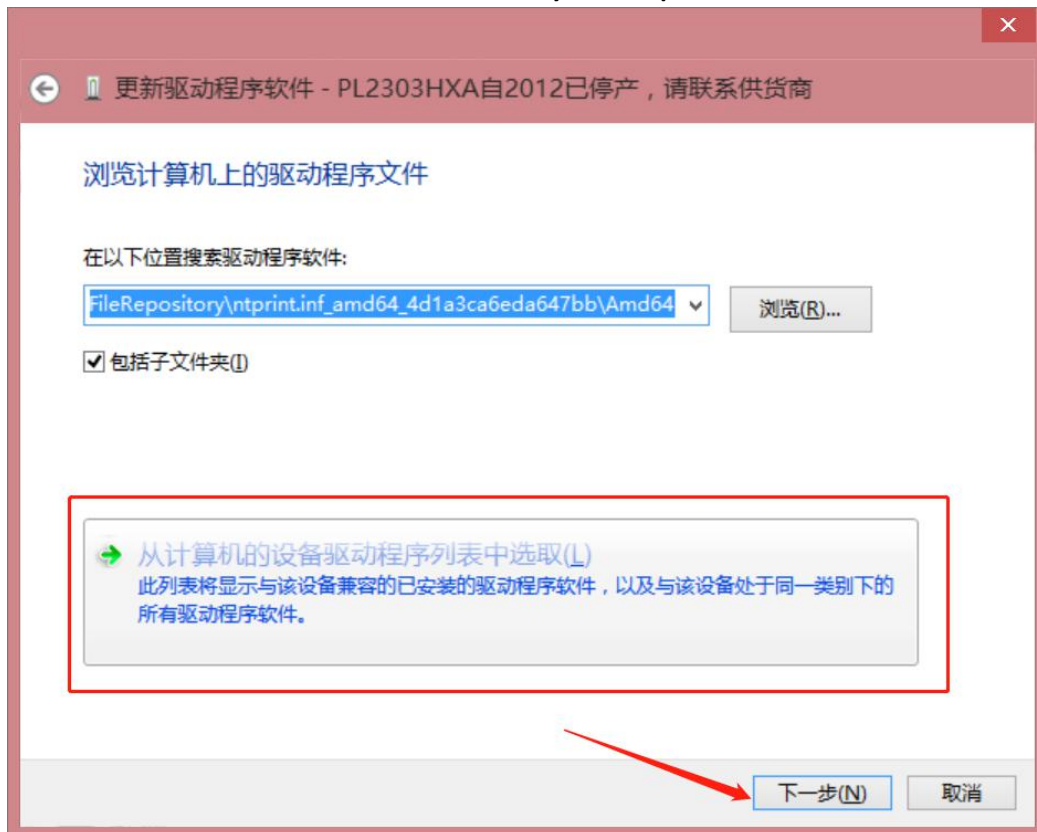
First step: Install driver PL2303_Prolific_DriverInstaller_v110



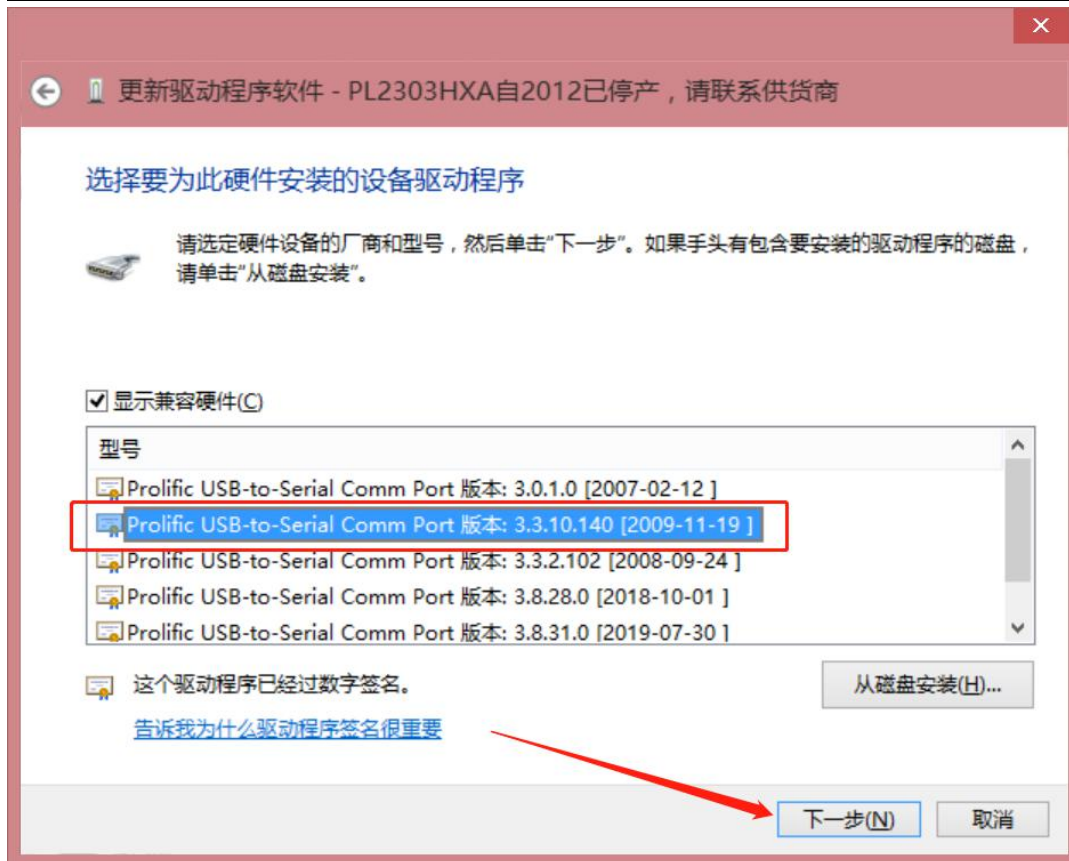
Second: Right click to update the driver and select Browse Computer to find the driver software.



Thrid: Click to select from the list of drivers for your computer;



Select version 3.3.10.140 (2009-11-19), click Next, close the window when finished;



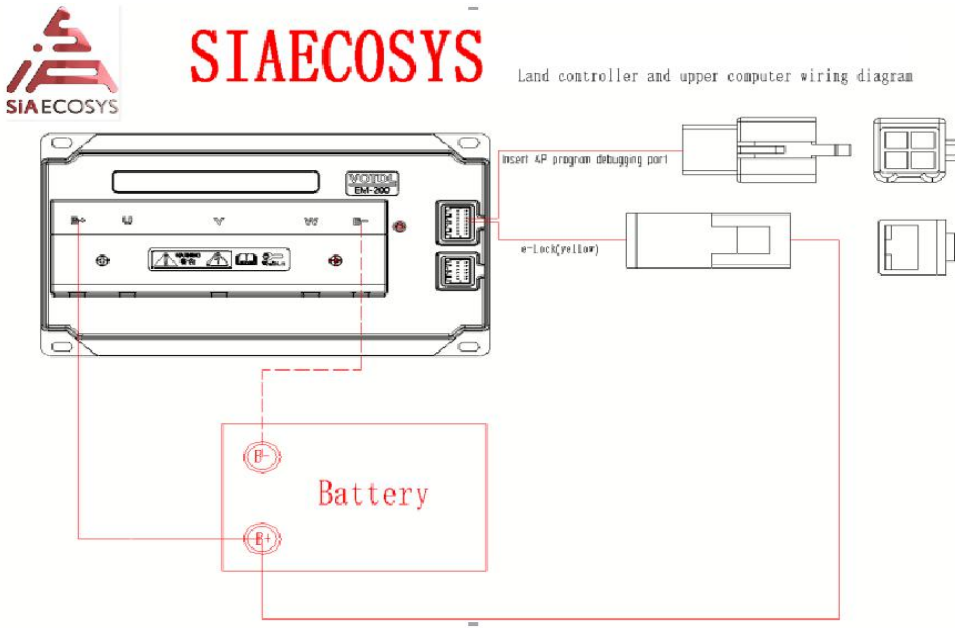
2. Controller connection

2.1 Connect controller

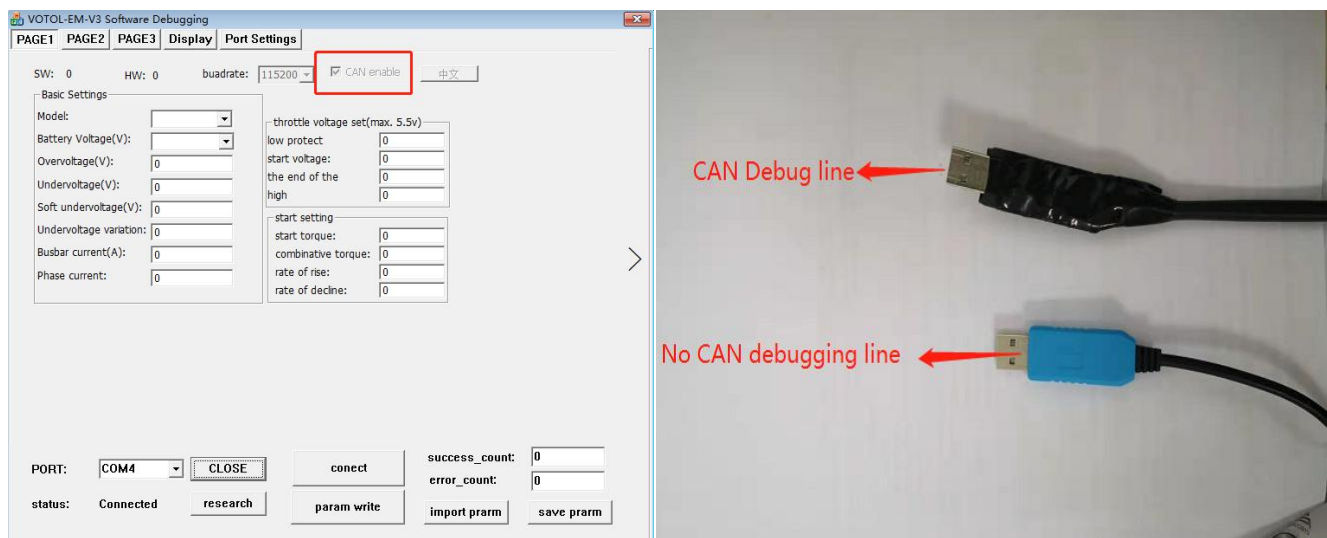
Controller host computer simple wiring diagram

Description: controller B+ connects battery B+ controller B-connects battery B-, controller electric door locks connect battery or controller B+;

The USB debug line is connected to the controller debug port;

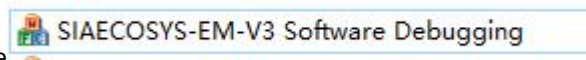


2.1.1 According to the controller with CAN or without CAN to select the appropriate USB debug line; with CAN controller need to check the CAN enable, without CAN does not need to check; EM200 controller needs to exchange the debug line CAN-H and CAN- L , otherwise can't connect the controller;

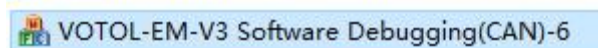


2.1.2 Host computer selection

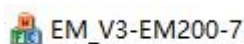
EM50 EM100 EM150 without CAN choose



EM50 EM100 EM150 with CAN choose



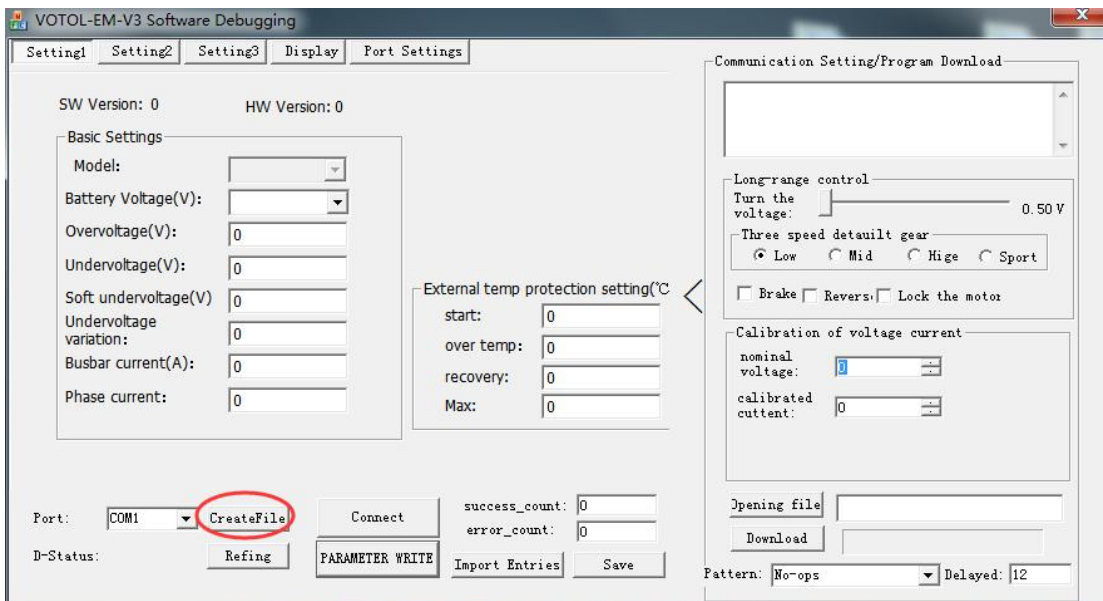
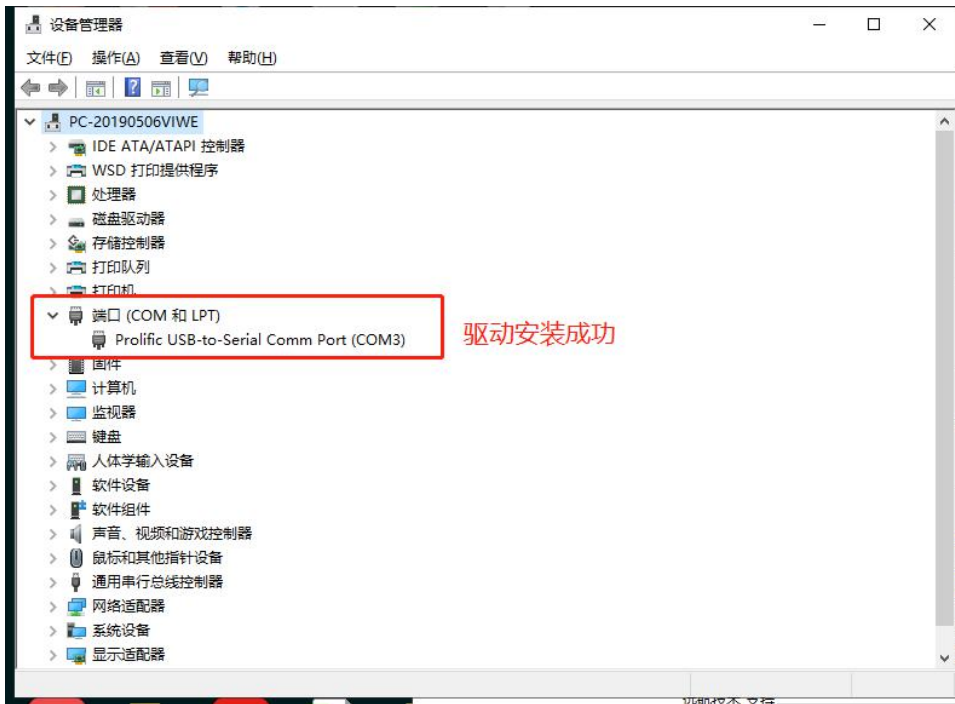
EM200 choose



Specific host model needs to inquire the related sales;

3 Open the computer device manager before connecting to the computer to check whether the USB port is successfully

installed. Select the appropriate host computer to connect the host computer to the serial port when the controller is not powered. After selecting the corresponding serial port on the device port, click CreatFile.



2.2

Then power on (connect with e-lock), click connect (in setting 1 page), the nominal voltage should not be 0. If it's 0, click connect again.

VOTOL-EM-V3 Software Debugging

PAGE1

PAGE2

PAGE3

Display

Port Settings

SW: 2.31 HW: 1.63 buadrate: 115200 ☒ CAN enable 中文

Basic Settings

Model: EM-150

Battery Voltage(V): 72V

Overvoltage(V): 91

Undervoltage(V): 64

Soft undervoltage(V): 67

Undervoltage variation: 1

Busbar current(A): 120

Phase current: 9960

throttle voltage set(max. 5.5v)

low protect 5.52

start voltage: 0.06

the end of the 1.59

high 5.32

start setting

start torque: 0

combinative torque: 37270

rate of rise: 0

rate of decline: 2

PORT: COM4

CLOSE

connect

status: Connected

research

param write

import prarm

save prarm

success_count: 23

error_count: 0

communicatin and download set

remote control

throttle: 2.78 V

L

M

H

S

switch

brake

revers

lock

calibration

vol cal: 1131

cur cal: 43

weak flux: 7

show err

open file

download

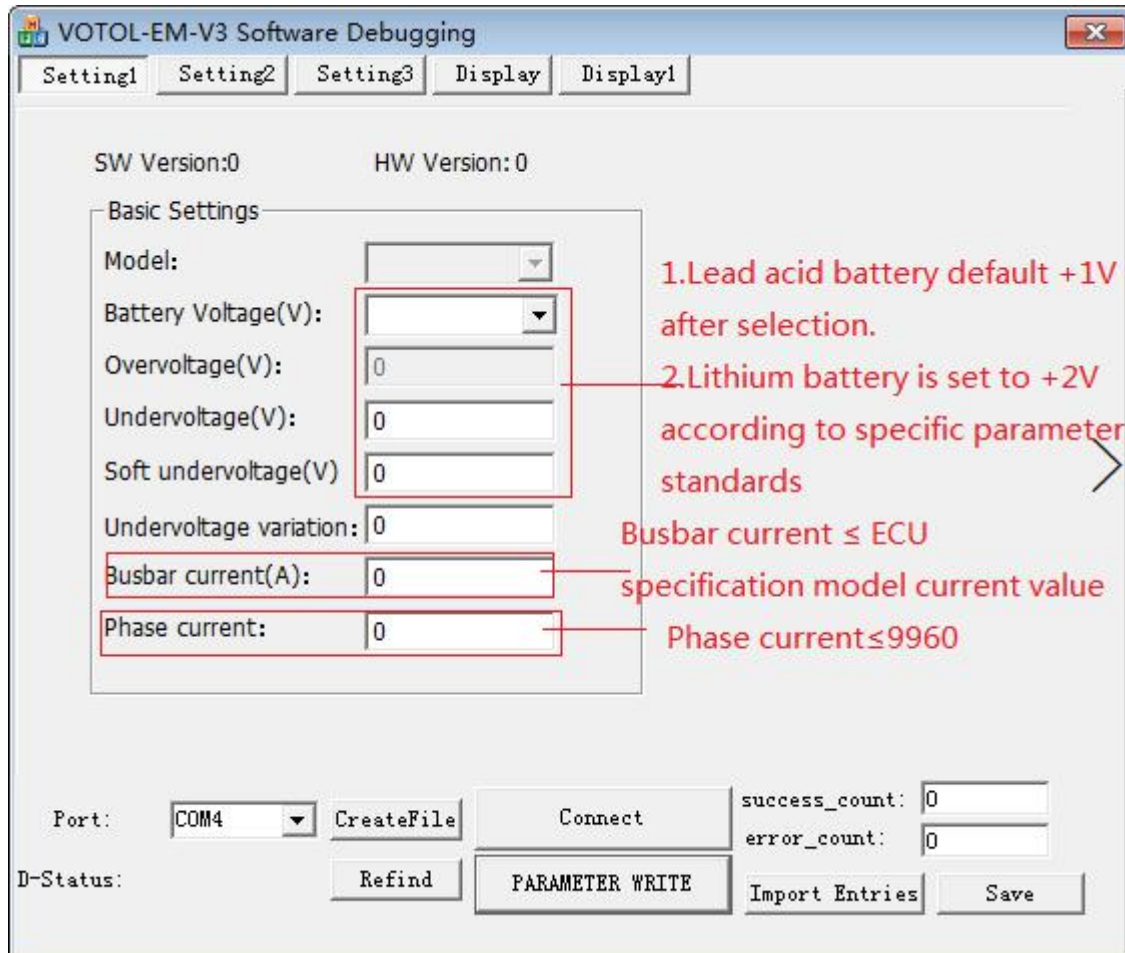
moden: No-ops

delay: 12

10

3. The setting

Setting page 1



1.1: Voltage equipment

- 1.1.1、 Battery voltage setting: Corresponding to the ECU voltage, absolutely not allowe overpressure.
 - 1.1.2、 Lead-acid battery overvoltage, undervoltage, soft undervoltage basic value default: due to software settings defects, the original voltage compensation +1V.
 - 1.1.3、 The lithium battery is set according to the actual lithium battery parameter value. Due to software setting defects, the original voltage compensation +1V. The original lithium battery parameters are compensated for +1V, and the total compensation is +2V.
 - 1.1.4、 Attention
 - 1.1.4.1、 Overvoltage fault: After open the electric door lock, the vehicle doesn't move. The Controller overvoltage protection function starts.
 - 1.1.4.2、 ECU undervoltage fault: due to the lithium battery protection board overvoltage device is too high or the undervoltage setting is too low, resulting in lithium battery protection, burning MOS. Please adjust suitable battery voltage before running the motor and controller(for lithium battery).
- Overvoltage: real overvoltage +3V
Undervoltage: real undervoltage +1V

Soft undervoltage: undervoltage + 3V

g. real overvoltage 84V, set 87V. real undervoltage 60V, set 61V. Soft undervoltage: 64V.

1.2: Current device

1.2.1、 Busbar current setting: The current is selected according to the ECU specification model.

VOLTAGE MODEL	EM-30S	EM-50	EM-50S	EM-100	EM-100S	EM-150	EM-150S	EM-200	EM-300
48-60V	33A	45A	50A	85A		120A	150A	200A	400A
72V	33A	45A	50A	85A	100A	120A	180A	200A	400A
84V	30A	45A		80A		120A			
96V		40A		70A		100A		180A	350A

1.2.2、 Phase current setting: can only be adjusted downwards.

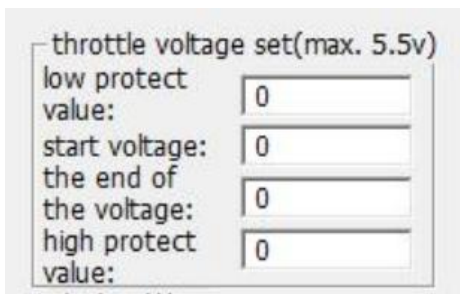
1.2.3、 Attention

1.2.3.1、 Setting the busbar current too high, causing the ECU burn MOS.

1.2.3.2、 **As the phase current value decreases, the corresponding motor stall protection time is shortened.**

Setting page 2

1 throttle voltage adjust



(1) low protection value: The throttle error is shown

(2) Starting voltage: when the value is reached, the motor starts running

(3) End voltage: when the value is reached, the controller thinks the full voltage is reached (it is recommended to set the voltage lower 0.2v compared with the actual torque voltage).

(4) High protection value: when the value is higher than that, the torque fault will be displayed

2 Start setting adjustment (for tricycle gear box only)

start setting

start torque:	0
combinative torque:	0
rate of rise:	0
rate of decline:	0

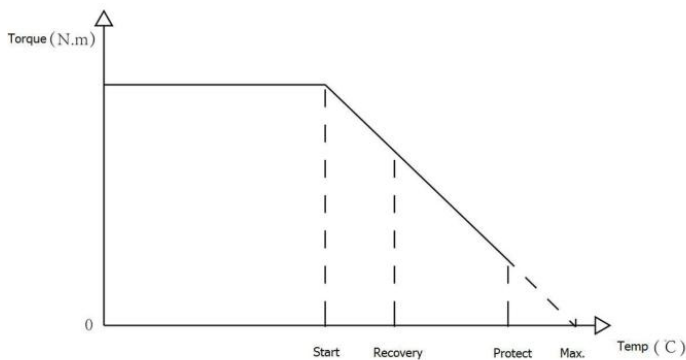
- (1) Starting torque: used for gear combination
- (2) Combined torque: a force of lifting after gear clearance is combined
- (3) Upward slope: upward slope of motor torque
- (4) Downward slope: downward slope of motor torque

3 Controller and motor temperature protection function adjustment

External temp protection setting(°C)

start:	0
over temp:	0
recovery:	0
Max:	0

- (1) Start: Enter into the function of temperature protection, limit the motor torque.
- (2) Over temperature: Cut off the output of motor torque
- (3) Recover: When the motor temperature lower than the temperature protection value, you can re-twist the throttle, then the motor will restore motivation
- (4) Maximum: The motor maximum temperature is 150



Setting for page 2

VOTOL-EM-V3 Software Debugging

PAGE1 | PAGE2 | PAGE3 | Display | Port Settings

1.NO/YES
2.Adjustable exit time

Single voltage default: low voltage is valid, high voltage is invalid
1.Low, medium and high speed settings within the motor base speed
2.Exceeding the basic speed of the motor belongs to the weak magnetic zone
Medium, high, and boost parameter settings are adjusted according to the motor model. (The third speed setting is the same as the boost parameter)
The smaller the value, the softer the start
Three choices
1.Two choices
2.If the speed limit is selected, it needs to be customized according to the manufacturer's function.

SPORT mode setup
Current-Limiting(A): 0
Flux-Weakening Value: 0 0
☐ Automatic logout enablers
Logout time(S): 0
Recovery time(S): 0

Flux-Weakening compensation: 0

Three-speed
Low(%): 0 0
Mid(%): 0 0
Hige(%): 0 0
Mid Flux-Weakening Value: 0 0
Hige Flux-Weakening Value: 0 0

Downhill electric brake assist(HDC/HHC)
☐ HHC Enable
☐ HDC Enable
HDC lowrst speed: 0

Speed limit setting
☐ Speed limited enable
Speed ratio(%): 0

Button/Switch 3 speed
☒ Button 3 speed ☐ Switch 3 speed
Three speed default gear
☒ Low
☐ Mid
☐ Hige

☐ Soft start enabled
Soft start grade: 1

PORT: [Dropdown] **OPEN** **connect**
status: **research** **param write** **success_count:** 0 **error_count:** 0
import prarm **save prarm**

3.1: Parameters setting for sports mode(S gear)

3.2.1、Busbar current setting: According to the controller type current corresponding to the selection, absolutely no overcurrent is allowed.

VOLTAGE MODEL	EM-30	EM-50	EM-50S	EM-100	EM-100S	EM-150	EM-150S	EM-200	EM-300
	S								
48-60V	35A	50A	55A	100A	----	200A	----	320A	550A
72V	35A	50A	55A	100A	150A	200A	250A	320A	550A
84V	33A	50A	50A	100A	----	180A	----		
96V	----	45A	50A	80A	----	130A	----	250A	500A

3.2.2、Sport mode flux weakening value: **Flux weakening value for S gear: the parameter value is <3000, and the vehicle speed is adjusted according to the motor parameters. BOOST weak magnetic value> high speed weak magnetic value**

3.2.3、Automatic logout enablers, confirm by select:Check the jog button / uncheck the long press button, choose one

3.2.3.1、 Check to make the jog effective. The weak magnetic time enters the exit and can be adjusted.

3.2: Downhill electric brake assist: start by select “HDC Enable”, downhill electric brake assist (slow down in steep slopes) function. Enable electric brake by enter minimum speed, if less than the speed, the function will be invalid.

3.2.1 Value 400 corresponding to speed around 15kmh(it depends on motor feature, sometimes with a

3.2.2、 Note: The drum motor is not suitable for use, resulting in loose motor shaft.

3.3、 Flux weakening compensation: only valid when the inner rotor motor type is selected as V-shaped magnetic steel

Note: The maximum value of 255 is generally filled in 95

3.4、 Three gear setting: Confirm the motor base speed value adjustment setting parameter value. The basic speed is filled in according to the <Appendix EM_V3 Parameter Adjustment Calculation Formula>.

3.4.1、 The low, medium, high, and third speed values are valid within 100% of the parameter value, and the medium, high, and high speed values are exceeded and the 100% parameter value is filled. Exceeded by weak magnetic file (medium, high, BOST)

3.4.2、 In the flux weakening area, the actual parameters of the motor are adjusted, and the vehicle speed is based on the road test.

3.4.3、 Single voltage mode: The high voltage value is invalid.

3.4.4、 Attention

3.4.4.1 、 Drum motor: 60KM/H motor weak magnetic speed is less than <120%, 80KM/H motor weak magnetic speed is less than <125%, 110KM/H motor weak magnetic speed is less than <135%.

2.4.4.3 Inner rotor motor Hall: The built-in Hall weak magnetic speed is less than <135%, and the external Hall weak magnetic speed is less than 170%.

3.4.4.3、 Internal rotor motor magnetic knitting: Built-in flux weakening speed <230%.

3.4.4.4 The motor base speed exceeds 100% of the motor speed value and enters the weak value zone adjustment parameter. BOOST>High speed weak magnetic file.

3.4.4.5 Weak magnetic failure: The flux weakening value exceeds the motor and controller parameter values, causing the motor to demagnetize and the controller to burn MOS.

3.5、 Jog/push selection: choose one

3.6、 The three-speed default gear: the electric door lock opens the default several options.

3.7、 Soft start setting: The smaller the value, the softer the start.

3.8、 Speed limit setting:

3.8.1、 Function selection: speed limit, unlimited speed, two choices, default speed limit

3.8.2、 The speed limit speed is calculated based on vehicle parameter requirements. <Appendix EM_V3 parameter adjustment calculation formula>

3.8.3 、 The upper limit speed and the solution speed limit are determined according to customer requirements.

Setting page 3

VOTOL-EM-V3 Software Debugging

PAGE1 | PAGE2 | PAGE3 | Display | Port Settings

Motor Setting

Pole pairs: 4

☐ exchange hall wire color Yellow-Blue

☐ exchange phase wire color Blue-Green

Hall shift Angle

Motor type

☒ surface-mount ☐ V-type

Out-put

☒ One-Lin ☐ Hall speedometer

☐ Moving vehicle booster ☐ Cruise

Moving vehicle booster

Speed ratio(%): 0

Moving vehicle booster torque: 0

Double voltage automatic identification setting

☐ Double-voltage ☒ Low ☐ Hige

Reversing the speed limit(%): 0

EBS ratio(%): 0

☐ Low beake ☐ Secure boot

success_count: 0

error_count: 0

PORT: [dropdown] OPEN

status: [dropdown] research

connect

param write

import prarm

save prarm

5-15km/h

40-70%

Fill in according to motor parameters

NO/YES

NO/YES

Tricycle motor reversing

Two choices

NO/YES

<3km/h

9-12n*M

Default high and low voltage selection

Choose double-voltage or not

Controller parameter write

Import existing prarm

3.1、 Motor Setting:

3.1.1、 Motor pole pairs: Fill in according to the motor manufacturer parameters.

3.1.2、 Hall phase shift angle: Fill in according to the motor manufacturer parameters.

3.1.3、 Motor type: Fill in according to the motor manufacturer parameters.

Note: Wheel Hub motor is surface mount

3.1.4、 Hall, phase line exchange: exchange the motor forward and reverse.

3.2、 The controller to speedometer date output has 2 types: Single-line speedometer and hall speedometer, it needs to be decided by the vehicle's speedometer.

3.3、 Moving assist and cruising function: Used in two-wheelers

Note: Speed "3KM / H, torque 9 ~ 19N.M

3.4 Cruise function: function selection, the default does not open.

3.5 Dual voltage setting: default single voltage。

Note: The dual voltage function speed parameter value is followed by the motor speed setting. Adjust the parameters on the setup page 2.

3.6、 Reversing speed limit: The calculation formula is adjusted with reference to the EM_V3 parameter adjustment calculation formula file.

Note: The speed of the two-wheeler is 5KM/H, and the tricycle is 15KM/H.

3.7、 Reversing, EBS setting, low brake selection, starting safety switch function。

3.7.1、 According to the weight of the vehicle (recommended within 30%)

3.7.2、 Two-wheeler 35~60 interval

3.7.3、 Two-wheeler 45~75 section

3.7.4、 Energy recovery with lithium battery parameter value equipment, the actual road test shall prevail. BMS protection results in burning MOS. Jianyi rushing discharge branch.

3.8、 Low brake enable: brake signal high and low brake, default high brake, check low brake.

3.9、 Safety Switch Function valid checked

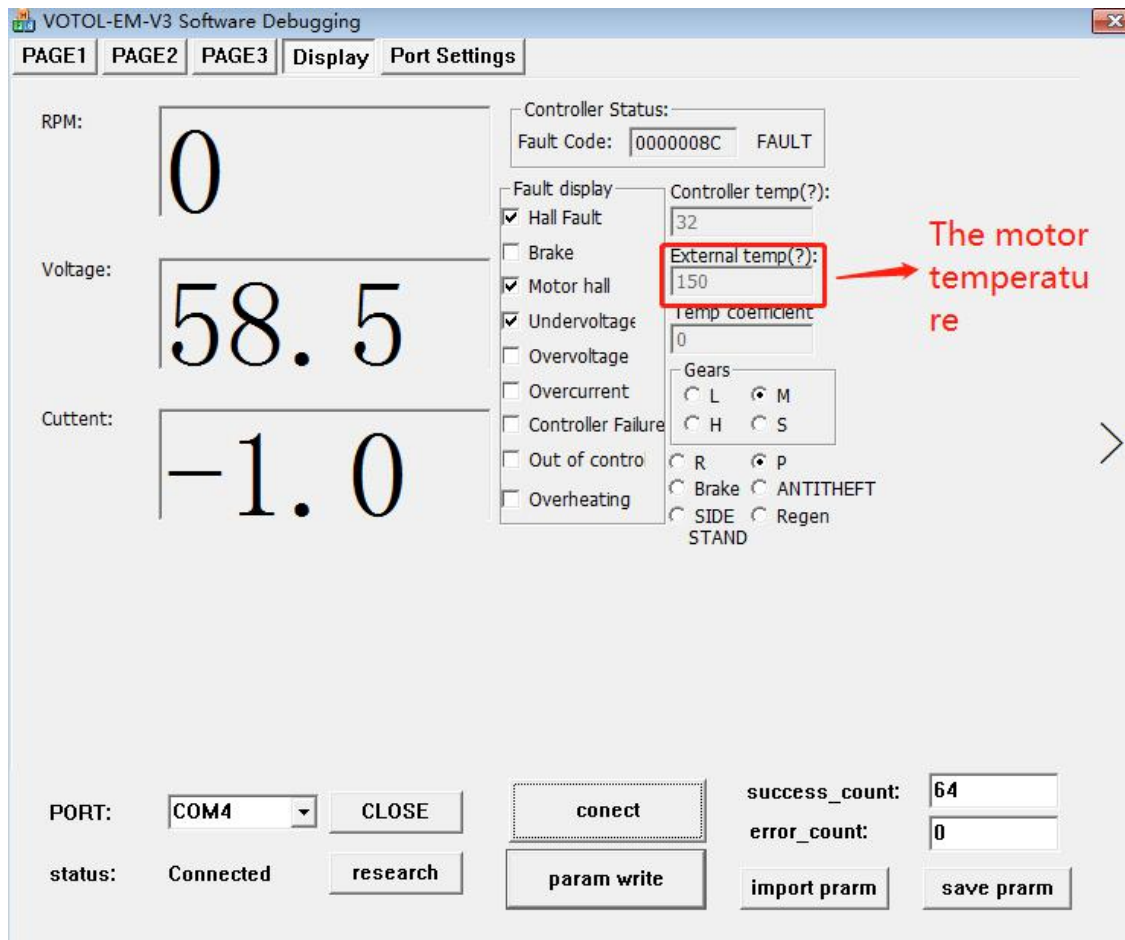
3.10、 Import configuration files: configured files are imported from the computer

3.11、 Save configuration file

Standard Edition: BZB/V39

Display page 4

External temps is the motor temperature



VOTOL-EM-V3 Software Debugging

PAGE1 PAGE2 PAGE3 **Display** Port Settings

RPM: 0

Voltage: 58.5

Cuttent: -1.0

Controller Status:

Fault Code: 0000008C FAULT

Fault display:

- ☒ Hall Fault
- ☐ Brake
- ☒ Motor hall
- ☒ Undervoltage
- ☐ Overvoltage
- ☐ Overcurrent
- ☐ Controller Failure
- ☐ Out of contro
- ☐ Overheating

Controller temp(?): 32

External temp(?): 150 → The motor temperature

Temp coeicient: 0

Gears:

- ☐ L ☒ M
- ☐ H ☐ S

☐ R ☒ P

☐ Brake ☐ ANTITHEFT

☐ SIDE ☐ Regen

STAND

PORT: COM4 CLOSE

status: Connected research

connect

param write

success_count: 64

error_count: 0

import prarm save prarm

Extended page

The screenshot shows the 'communication and download set' window. It includes fields for 'set compare check value' (8926) and 'current check result value' (8926). The 'remote control' section has a throttle slider at 0.50 V, radio buttons for L, M, H, and S, and checkboxes for brake, revers, and lock. The 'calibration' section has input fields for 'vol cal' (1131), 'cur cal' (43), and 'weak flux' (43), along with a 'show err' checkbox. At the bottom, there are 'open file' and 'download' buttons, a 'moden' dropdown set to 'No-ops', and a 'delay' field set to 12.

4.1、 Update the upgrade ECU program.

4.1.1、 Open the "BIN" file on your computer and download it to the ECU.

Click open file, select the file type as BIN format, click download to 100%;

This screenshot shows the same software interface as the previous one, but with the 'download' button highlighted. Below the button, a progress bar is shown at 100% completion. The file path 'C:\Users\YLB\Desktop\EM_V3.bin' is visible in the file selection area.

4.1.2、

insert the line by model and plug in the computer. The line is divided into the following models:
EM-30~EM-150 universal, EM-200, EM-300, CAN

4.1.3、 Attention:

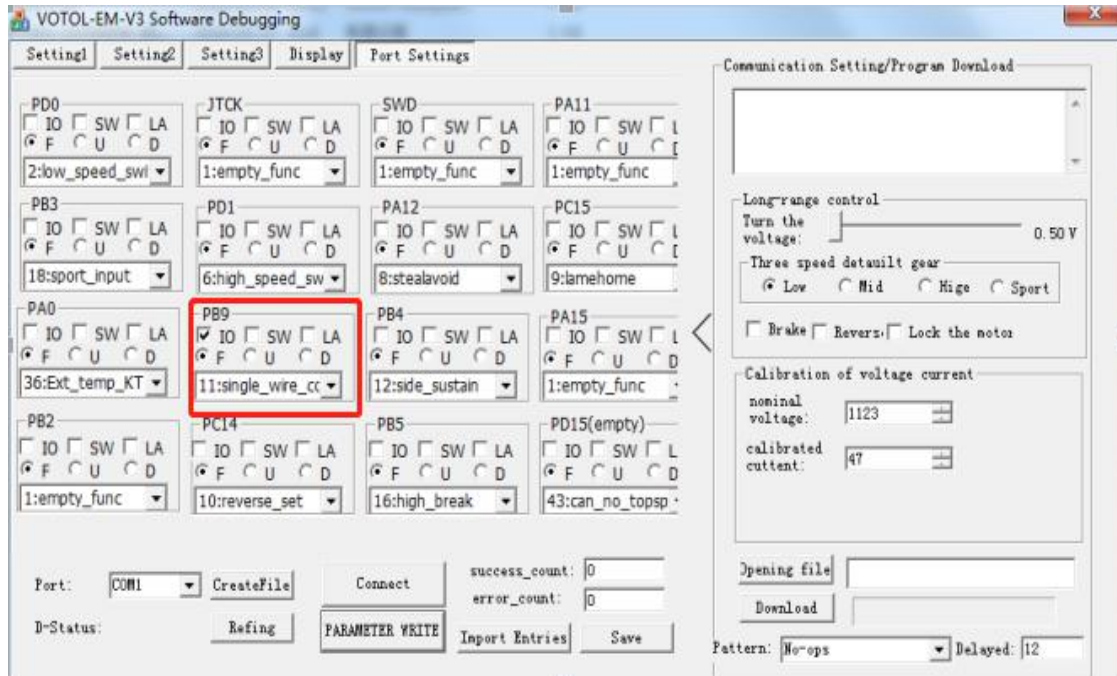
4.1.3.1、 Use USB isolation dedicated line. It is not a dedicated isolation line that burns the ECU port and the computer.

4.1.3.1、 The ECU is not read completely, and the ECU is connected several times in the setup meeting.

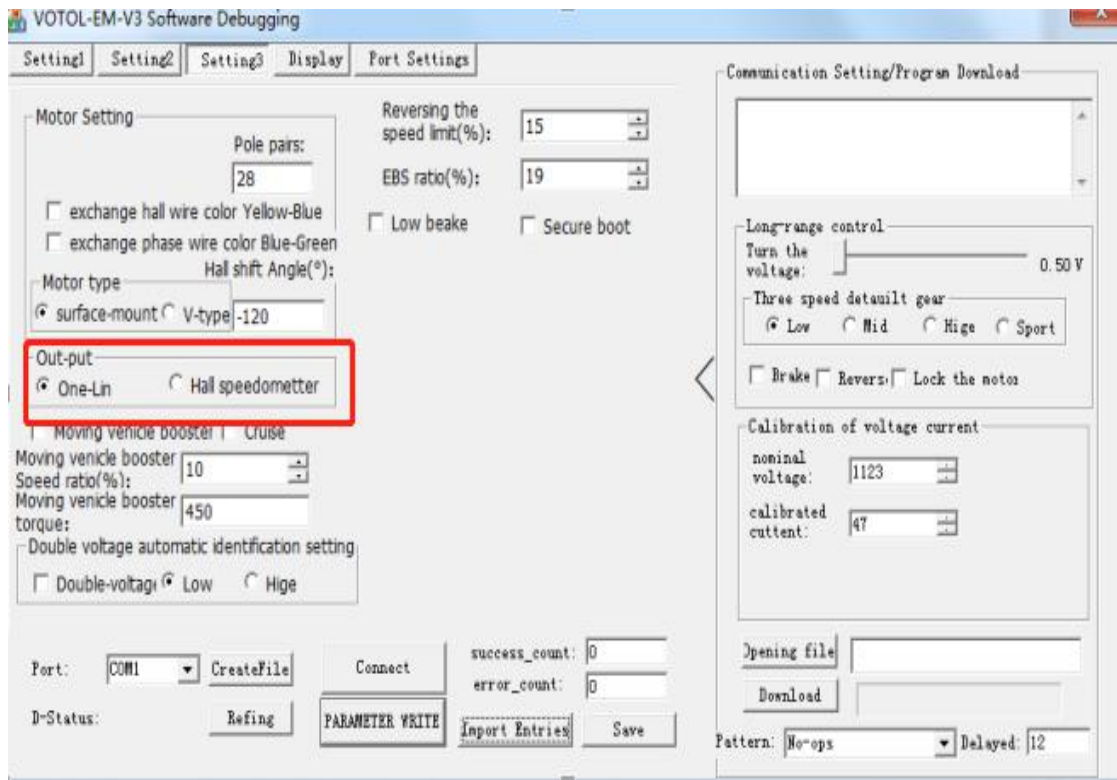
Port setting

1. One-line setting

PB9 choose 11

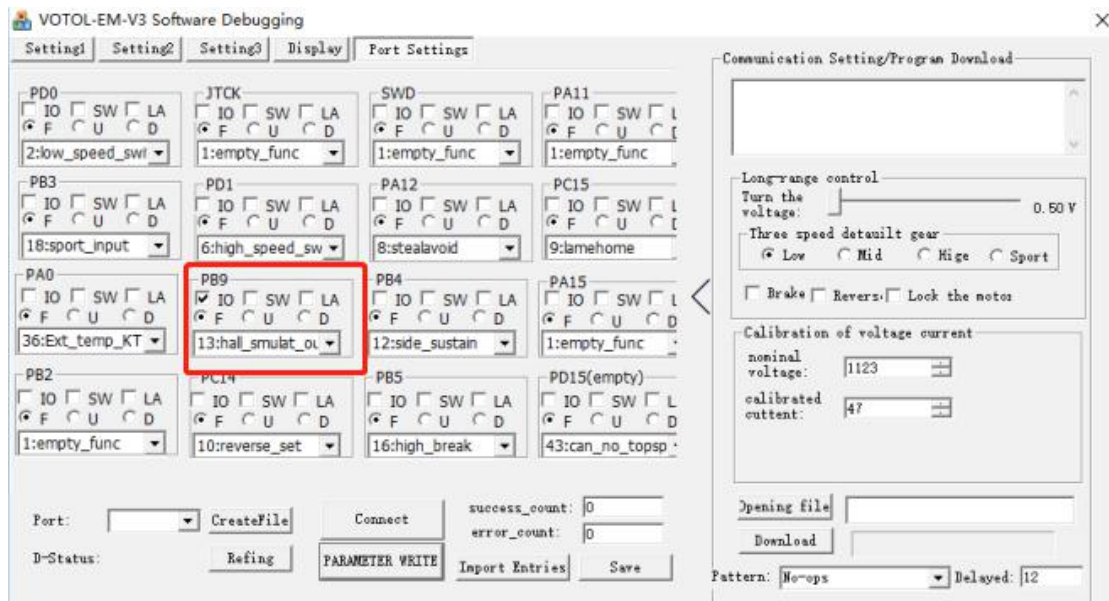


Output choose one- Lin

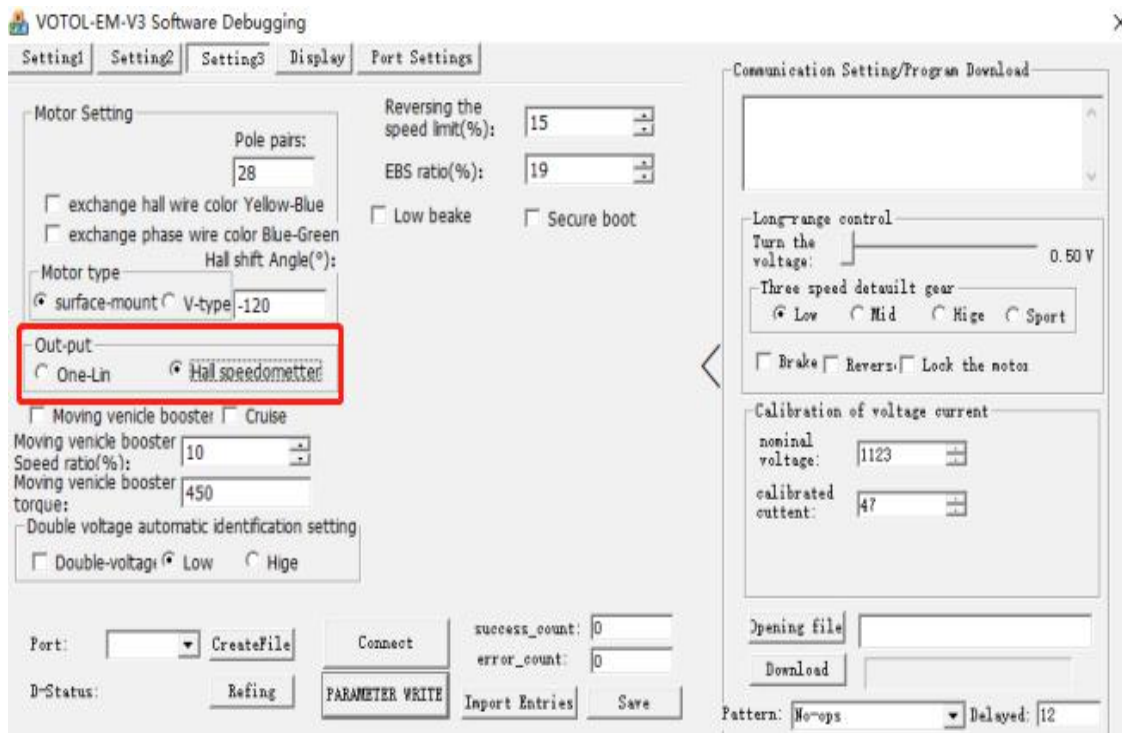


2.Hall setting

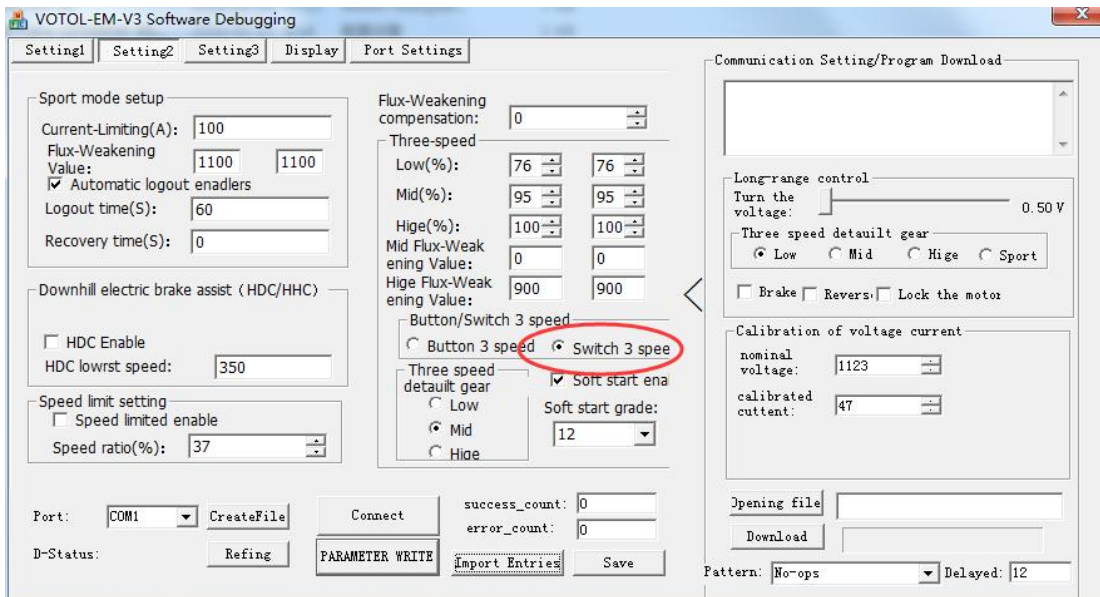
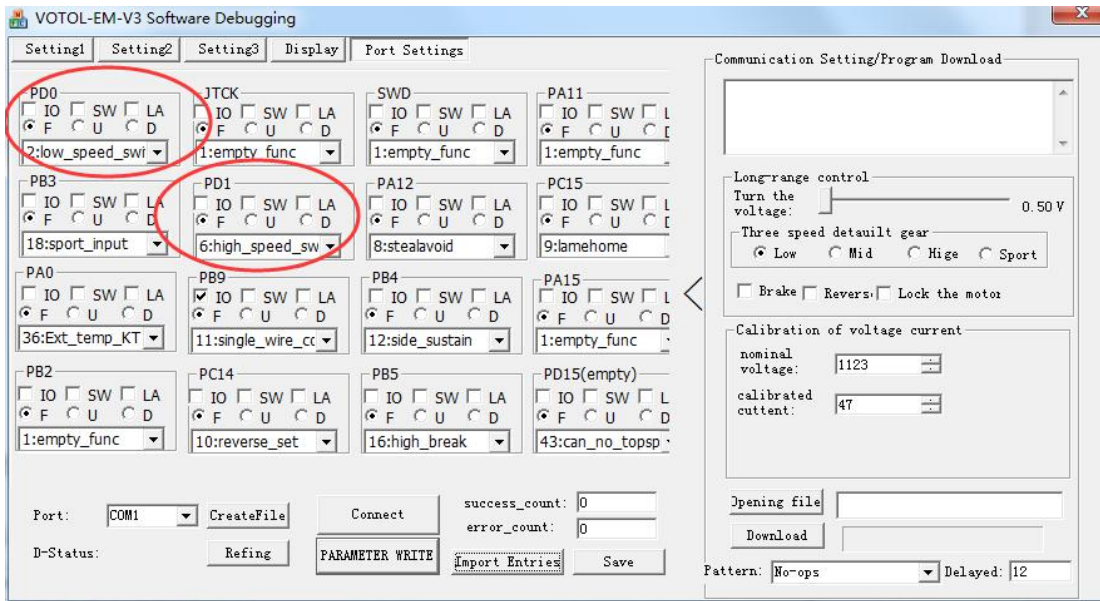
PB9 choose13



Output choose hall speedometer

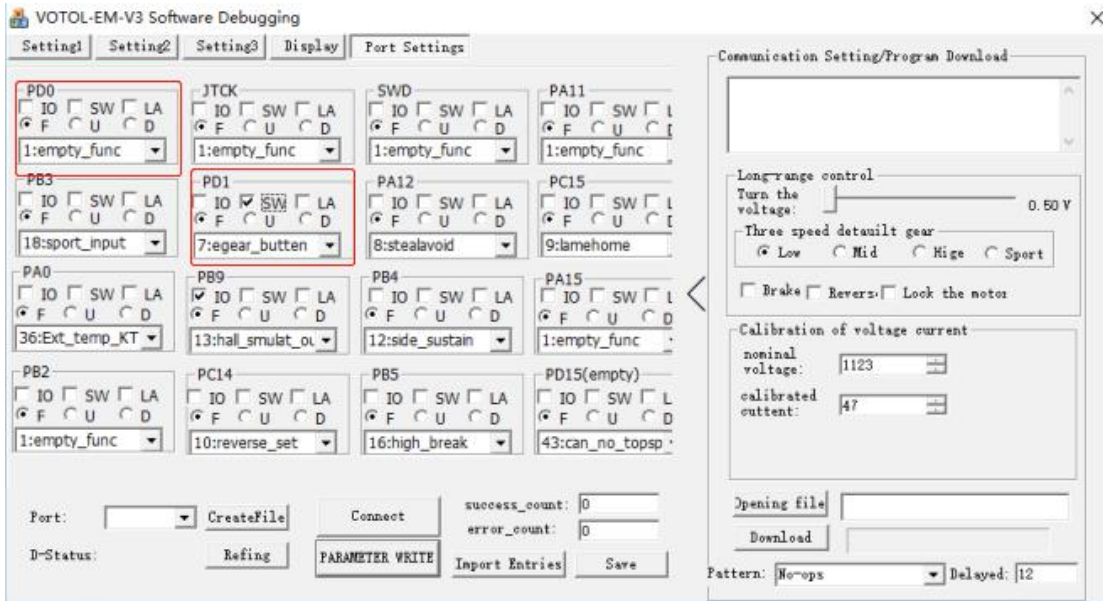


3. Trigger three-speed setting

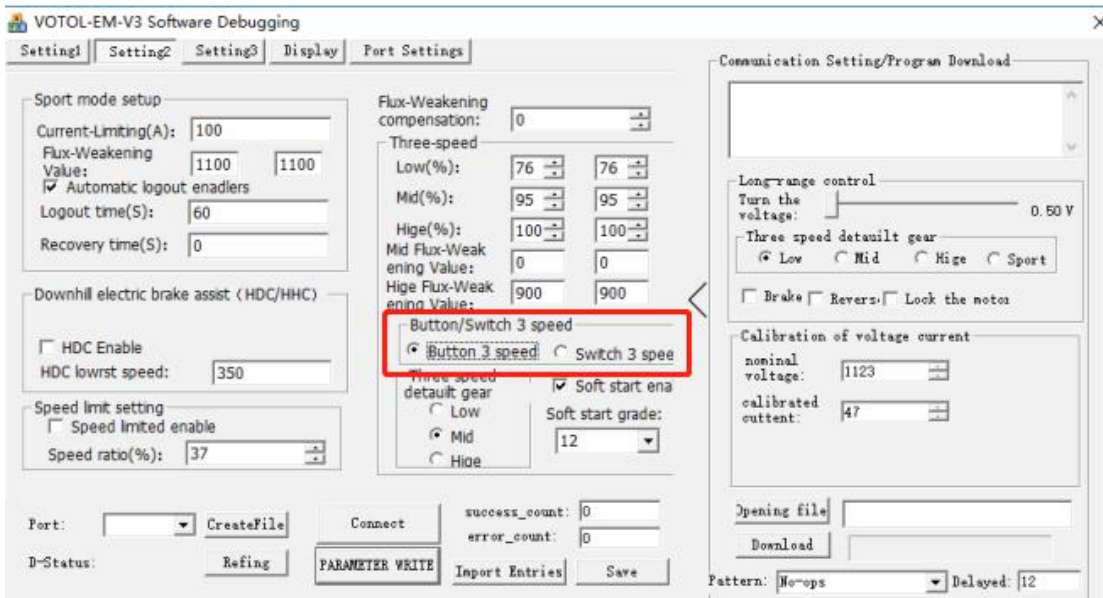


4. Jog three-speed setting

PD 0 PD1 SW choose 7

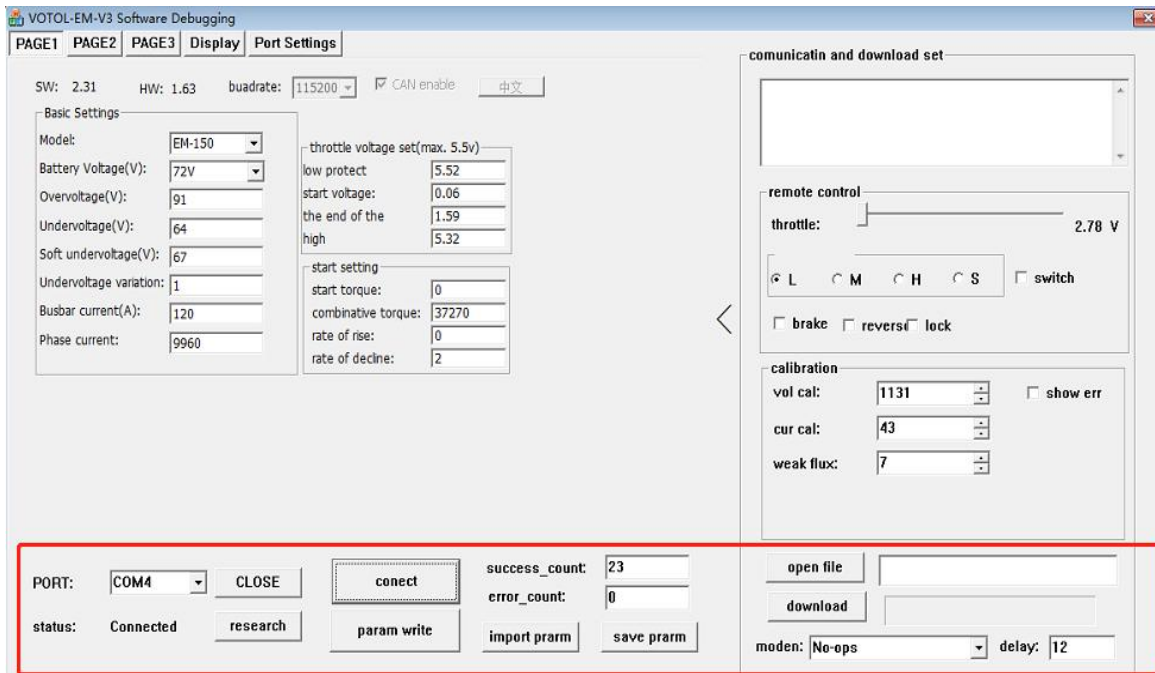


Choose Button 3 speed



5. To import the configuration, click import prarm, select the appropriate INI file, and then click param write; to export the configuration, click save pram and save;

After adjusting the parameters, click paparam write to save the parameters;



VOTOL-EM-V3 Software Debugging

PAGE1 PAGE2 PAGE3 Display Port Settings

SW: 2.31 HW: 1.63 buadrate: 115200 ☒ CAN enable 中文

Basic Settings

Model: EM-150

Battery Voltage(V): 72V

Overtvoltage(V): 91

Undervoltage(V): 64

Soft undervoltage(V): 67

Undervoltage variation: 1

Busbar current(A): 120

Phase current: 9960

throttle voltage set(max. 5.5v)

low protect: 5.52

start voltage: 0.06

the end of the: 1.59

high: 5.32

start setting

start torque: 0

combinative torque: 37270

rate of rise: 0

rate of decline: 2

remote control

throttle: 2.78 V

☒ L ☐ M ☐ H ☐ S ☐ switch

☐ brake ☐ reversel ☐ lock

calibration

vol cal: 1131 ☐ show err

cur cal: 43

weak flux: 7

PORT: COM4 CLOSE connect success_count: 23

status: Connected research param write import prarm save pram error_count: 0

open file download moden: No-ops delay: 12

Remarks: Please carefully read this attentions before the user adjusts the parameters. Since the user does not adjust the parameters according to the precautions, the controller is not responsible for the after-sales of such controllers.